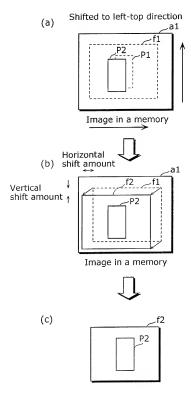
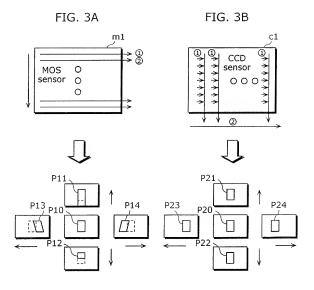
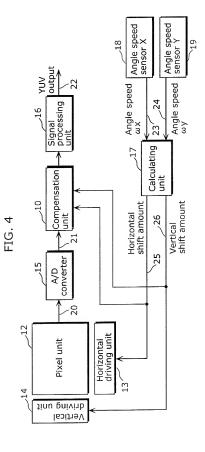


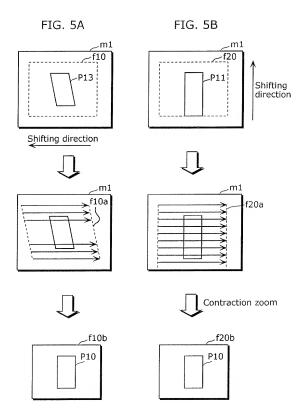
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FIG. 2









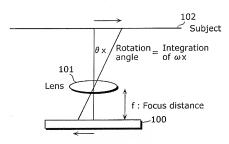
Angle speed sensor y

19

Angle speed sensor x

Angle speed sensor x

FIG. 7A



Horizontal shift amount= $f*tan(\theta x)$ 

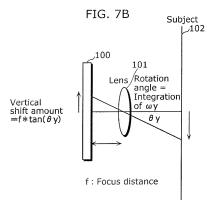


FIG. 8

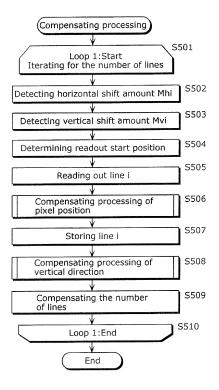


FIG. 9A

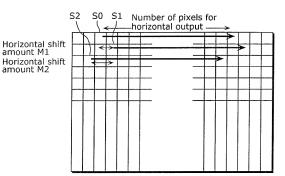


FIG. 9B

Horizontal shift amount M1 Horizontal shift amount M2 Horizontal shift amount M3

R	G	R"	G	R	G		R	G	R	G	R	G
G	В	ଙ୍	В	ন্ত	В		G	В	G	В	G	В
R	G	R*	G	₹	G		ĸ	G	K.	ď	R	G
G	В	G	В	¥5	В		G	В	G	В	G	В
R	G	R	G	R	G		R	G	R	G	R	G
G	В	G	В	G	В		G	В	G	В	G	В
						1800-00-00-00-00-00-00-00-00-00-00-00-00-						

FIG. 10A

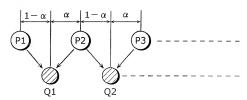


FIG. 10B

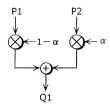
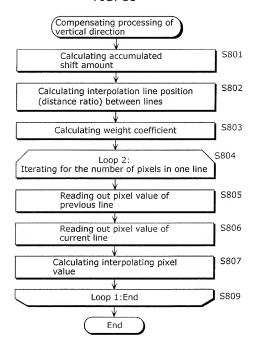
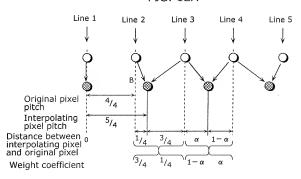


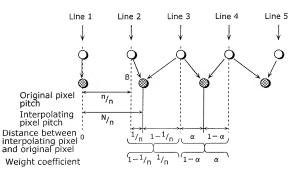
FIG. 11



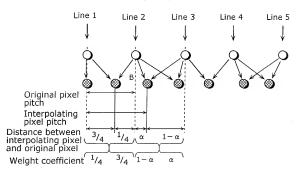




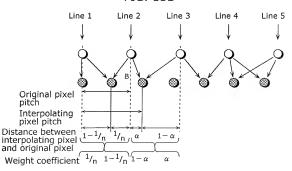
## FIG. 12B



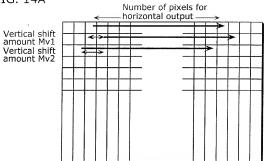




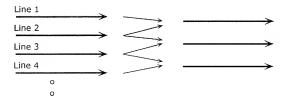
## FIG. 13B



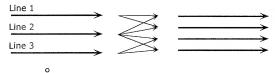




## FIG. 14B



## FIG. 14C



0

FIG. 15A

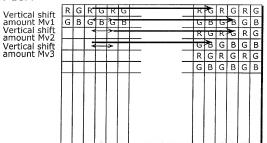
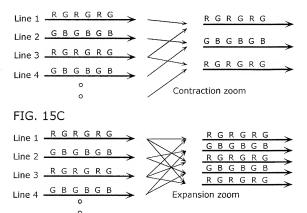
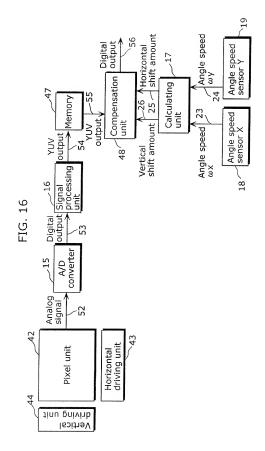


FIG. 15B





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FIG. 17

